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Abstract of the DisclosureOPERATOR INTERFACE SYSTEM

5           In the operation of work machines it has  
been a problem to control the work machine's velocity  
aspects such as velocity, acceleration, deceleration  
and jerk because of the plurality of operator  
interfaces required for such control. The present  
10 invention provides an operator interface system for a  
work machine in which a first pedal is displaceable  
from a neutral position, and a sensor is operatively  
coupled with the first pedal and is operable to output  
a displacement signal corresponding to a location of  
15 the first pedal. An electronic controller receives  
the displacement signal and provides a pre-determined  
control to a velocity aspect of the work machine in  
response to the displacement signal.